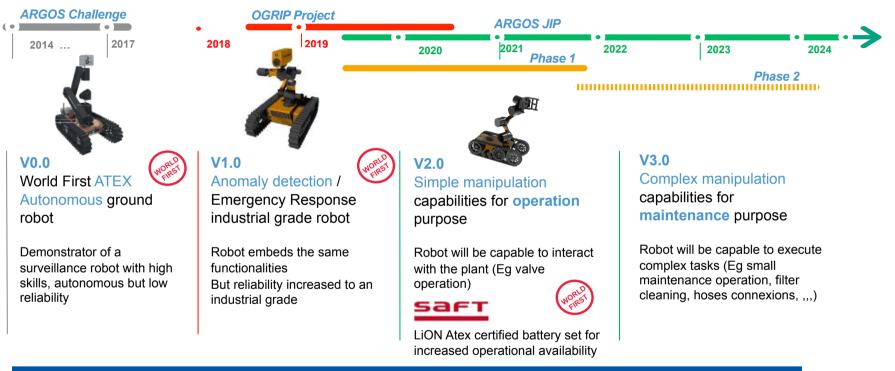


ROBOT DEVELOPMENT ROAD MAP



Autonomous - ATEX - Water Resistant - Mobile - Multipurpose - Remotely Monitored - 24/7 Service



Design & qualify autonomous ground robots able to operate remote sites





ANOMALY DETECTION ROBOT (V1.0 – OGRIP*): GENERAL ARCHITECTURE



Anomaly detection

- Audio (leaks, signature)
- Hot spots & fugitive emissions
- Gas detection
- Obstacles (+/-)

Process

- · Dial gauge reading
- Valve position

Mapping - Creation of 3D map

*OGRIP: Offshore Ground Robot Industrial Pilot, commercial name The Taurob Inspector





TESTS IN SHETLAND (UK): SITE DESCRIPTION

Shetland Gas Plant

- Gas treatment for Laggan Tormorre subsea fields
- Condensate extraction, gas drying (MEG), compression (3 turbo compressors, LM2500)
- Start up in 2016

Climatic conditions

- Windy and exposed to sea water (spindrifts)
- Good candidate to simulate offshore environment









TIMELINE OF SHETLAND GAS PLANT PILOT

OGRIP project













Start of OGRIP March 2018

- Site surveys & preparation
- Missions planning
- Design of new robot

Sept, 2018

- Ground testing
- Stair climbing
- 4G network
- Cloud connection
- Teleoperated

May, 2019

- OGRIP prototype
- Autonomous missions
- Teleoperated stair climbing
- 3D model scan
- Pictures to the cloud

August, 2019

- Autonomous stair climbing
- Autonomous missions
- Real time machine learning in the cloud

Feb, 2020 Total Investors Day

• Live demos of autonomous missions in front of investors

Oct, 2020 Start of Long duration operation - 1 year

- Hand over of robot to the plant
- 1 year in routine operations
- Day to day feedback
- REX & learnings
- Failures identification





TESTS ON K5 (OFFSHORE NETHERLANDS)

K5CC

- Gas production platforms with condensate recovery
- Located Offshore the Netherlands

Tests performed:

- Conduct autonomous missions in condensate recovery area
- Conduct a Proof Of Concept for external corrosion and painting inspection
- Evaluate use cases on the platform





World First
Autonomous Robot on an offshore O&G platform





ARGOS JIP PHASE 1 - SIMPLE MANIPULATION ROBOT EXECUTING ROUTINE PRODUCTION OPERATION TASKS



Operating valves designed as per API REC 6D (up to 150 Nm) Pushing **any buttons** (e.g. ESDV reset)

Sampling

Cleaning cameras, fire detectors

Moving Objects - Placing sensors (Eg: vibration)

Opening pig trap doors

Depressurization of well annulus

Chemical transfer from tote tank - Connecting Hoses

Exchanging Spare Parts











Typical use cases for wellhead platform or wellpad in NUF mode





TESTS IN TADI (LACQ, FRANCE)

Objectives

- Intensively run and test robots on a specifically created obstacle course site
- Test robot's adaptation to an EP environment (specs & new site ergonomic)
- Test integration of robotics in Total digital environment
- Test of new HMI for robot supervision by operators
- Map operating envelop deliver robots handbook

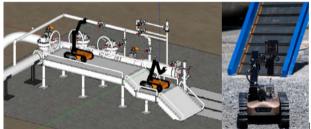
Opportunities

- Trials & errors
- Training
- Be a showroom

Examples of Tests

- Mobility and battery: stairs climbing optimisation, battery duration, new design for installations
- Operating envelop measurement
- · Gas leak: emergency response support
- · Operation reporting reliability



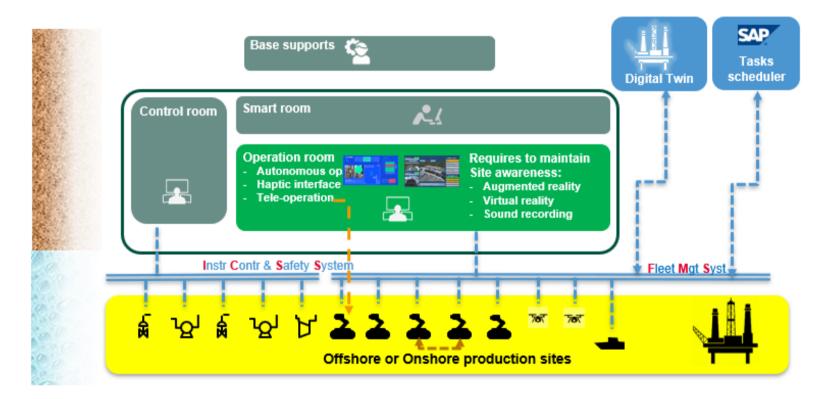








REMOTE OPERATIONS FOR NUF - FLEET MANAGEMENT



Supervision Context : Routine Operation / Anomaly Management / Emergency Response





LOCATION OF DEPLOYMENT OF ROBOTS FOR TESTS ON TOTAL'S FACILITIES



- Lacq: 2014 ARGOS Challenge
- Shetlands: 2018 OGRIP
- Tempa Rossa: 2018 JIP technical preparation
- Lacq: 2019 Launch of Robotics Development platform
- Netherlands: 2020 First autonomous ATEX robot offshore in O&G



QUESTIONS?





BACK UP: FEW PUBLICATIONS & USEFUL LINKS

ADIPEC 2019: presence, publications & presentations

- ✓ SPE-197620-MS: Ground Robotics Enabler for Normally Unattended Installations
- ✓ SPE-197513-MS: Normally Unattended Installations, the New Frontier for Cost Reduction
- ✓ Robot on Total stand with videos, live demos from Taurob lab in Vienna (our robotic partner)



ARGOS brochure: Ground Robotics For Next-Generation Facilities 2014-2019
CNBC article and video "Getting ready for robot-operated oil rigs" in June 2019

https://www.cnbc.com/advertorial/2019/08/12/getting-ready-for-robot-operated-oil-rigs.html

Articles & Videos on Total site "Ground Robots: Technological Building Block for the Surveillance of Oil and Gas Sites"

2019: https://www.ep.total.com/en/innovations/research-development/ground-robots-key-future-architectures

2017: https://www.total.com/news/argonauts-robot-wins-argos-challenge

Video Meet OGRIP V1.0 Oct 2019: https://www.youtube.com/watch?v=E7svE6ITN-g

Video TOTAL ARGOS Challenge: Winning Team, July 2017: https://www.youtube.com/watch?v=-jPL-bSj0TY

The Press release made by our JIP sponsor OGTC and few articles that followed the release, Oct 2019

https://www.theogtc.com/newsroom/news/2019/industry-innovators-and-key-technology-developers-lead-the-way-with-robotics-development/

Oilfield Technology - https://www.offshore-technology.com/news/oatc-offshore-robot-development/

Rigzone - https://www.rigzone.com/news/offshore_robot_initiative_wins_pledges_from_operators-21-oct-2019-160112-article/

Offshore Magazine - https://www.offshore-mag.com/business-briefs/article/14068984/equinor-enters-offshore-robotics-consortium

Launch of OGRIP project, April 2018

DIGIT: Article and Video, - https://digit.fvi/ogtc-robotics-trial/

Partner Web site

https://taurob.com/





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